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50R-400-ALT

480VAC Application, Panel Mount





Description

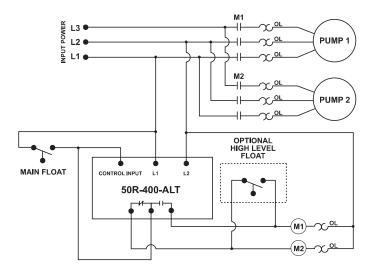
The 50R-400-ALT alternating relays are used to alternate between two loads, most commonly in duplex pumping and compressor applications to balance the runtime of both loads.

When used in single float applications, the alternating relay changes state after the float switch opens*, forcing the other pump to run the next time the float closes. When used in dual float applications, the alternating relay will allow both pumps to run simultaneously when the lead and lag floats are both closed.

An adjustment knob provides the option to force one pump to run every time the float switch is closed. This is helpful when one pump has been removed for repair or for test purposes.

A built-in debounce feature prevents the alternating relay from changing state if the float contact bounces momentarily.

Wiring Diagram



For dimensional drawing see: Appendix, page 509, Figure 6.

Features & Benefits

FEATURES	BENEFITS
Debounce time delay	Prevents rapid cycling caused by waves or splashing in the tank
LED indicators	Visual indication of load operation in duplex application
Built-in manual switch to force load operation	Helpful to control load operation when performing periodic maintenance or pump repair
Operates from 380 - 480VAC	No transformer required to provide 120 - 240V for control circuit

Specifications

Input Characteristics

Supply Voltage380-480VACSupply Current40mA

Functional Characteristics

Control Input Impedance (min) $1M\Omega$

Output Characteristics

Output Contact Rating

Pilot Duty 470VA @ 600VAC

General Purpose 10A

Debounce Time Delay 1 second

General Characteristics

Maximum Input Power 5 W

 Terminal
 7 in.-lbs.

 Wire Size
 12-18AWG

Safety Marks

UL UL508 (File #E68520)

CE IEC 60947

Dimensions H 74.4 mm (2.93"); **W** 133.9 mm (5.27");

D 74.9 mm (2.95")

Weight 0.98 lb. (15.68 oz., 444.52 g)

Mounting Method #8 screws

^{*}The alternating relay will not switch states while current is flowing. Switching will only occur after current has been sensed, followed by loss of current for the duration of the debounce time delay.